

# 5 Watt

# 3dprintable Wind Turbine.

#### Product Liability Waiver

This agreement releases '3dp' from all liability relating to injuries that may occur during the use of this Prototype Wind Turbine. By downloading the plans for this Prototype you agree to hold '3dp' entirely free from any liability, including financial responsibility for injuries incurred.

The user acknowledges the risk involved in operating a product of this type. These include but are not limited to the release of highenergy debris or electric shock. The buyer participates voluntarily, and accepts all risks.

By downing these plans you understood and agree to the above terms.

# Introduction

This document contains the Manufacturing, Assembly and Operational instructions for 3dp's Wind Turbine.

This fully functional wind turbine has been specifically design to be manufactured, assembled and operated at home with its unique 3d printable design. The wind turbine is optimized to produce a power output of 5 Watt (12volt ~4amps) at 5m/s wind speeds, perfect for battery charging applications.

The wind turbine has been designed with a unique Passive Variable Pitch (PVP) design. The PVP maintains an optimum power output through control of the turbines rotational speed. Whilst optimizing power output the PVP also protects the Turbine from dangerous over speed conditions, limiting its maximum revolutions per minute in wind speeds greater than 5m/s.

The main components of the turbine have been designed for Additive Layer Manufacturing (ALM) methods using PLA plastic. 95% of the ALM components require no post processing as these parts do not require 'print supports' reducing material usage whilst improving the overall finish of the part. The MkII has three design improvements, the first is an all important tail fin to allow the turbine to turn into the wind and extract the maximum wind energy in changeable conditions, the second is a stiffer tower structure with bigger bearings and increased diameter locating pin to support the increased loads from the tail whilst allowing for the third improvement which is the inclusion of Split Ring Electronics. The Split Ring Electronics allows the turbine to spin around the tower axis without any limitations it brings the power electronics into the tower where there is more space and its easier to access.

The MkII requires the following new parts:

- Structure
- Rear Structure
- Tower Header
- Nacelle





2

PRINTED	QTY.
ASSEMBLY DRAWING	1
ASSEMBLY DRAWING	1
ASSEMBLY DRAWING	1
Y	1
Y	1
	2
	1
	4
Y	1

F

Е

D

С

В

А





2

PRINTED	QTY.
Y	1
Y	1
Y	1
Y	1
Y	1
	1
	4
	2
	2
	2

F

Е

D

С

В

А

NEMA Stepper motor wiring routed here.



SECTION B-B SCALE 1 : 1

2



2
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## Tower Assy Drawing

rt number	PRINTED	QTY.
poter	Y	1
eader	Y	1
ole		1
haft	Y	1
wer Bearing		2
		1
D-Ring Setting		1

F

Е

D

С

В

А





# 2

F

Ε

D

С

В

А



# 2 Blade Drawing

F

Е

D

С

В

А

insert M5 nut. Before resuming the print ensure the nut is below the print surface.

2



#### **BILL OF MATERIAL**

					Shell thickness		1.2mm	
				1	Bottom/Top Th	ickness	1.2mm	
Component requires an e	mbedded n	ut, see blade drawing.				Pri	int Settings	
Description	Item No	Part Name	Printed	ΟΤΥ	Layer Height	Fill Density	Print Speed	Support type
Description				<u> </u>	(mm)	(%)	(mm/s)	Support type
	1	Tower Assy	NA	1				
	2	Structure Assy	NA	1				
	3	Rotor Assy	NA	1				
	4	Shaft Nut	Y	1	0.1	100	20	None
Wind Turbine Assembly	5	Nacelle	Y	1	0.1	30	50	None
	6	M3 12mm	N	2				
	7	M6 300mm Threaded Rod	N	1				
	8	M6 Nut	N	4				
	9	Tail Fin	Y	1	0.1	15	50	None
	1	Tower Footer	Y	1	0.3	30	50	None
	2	Tower Header	Y	1	0.3	30	50	None
	4	Tower Shaft	Y	1	0.1	80	50	None
Tower Assy	3	Tower Pole	N	1				
	5	Tower Location Bearing	N	2				
	6	Slip Ring	N	1				
	7	O-Ring	N	1				
	1	Structure	Y	1	0.1	50	50	None
	2	Stepper Motor Bracket	Y	1	0.1	100	50	None
	3	Generator Cog Driven	Y	1	0.1	100	20	None
	4	Generator Cog Driving	Y	1	0.1	100	20	None
Structuro Acov	5	Structure Rear	Y	1	0.1	50	50	None
Structure Assy	6	Stepper Motor NEMA11	N	1				
	7	M3 12mm	N	4				
	8	M3 25mm	N	2				
	9	M4 25mm	N	2				
	10	Main Location Bearing	N	2				
	1	Disc	Y	1	0.1	70	50	None
	2	Crank	Y	3	0.1	100	20	None
	3	Pitch Arm	Y	3	0.1	100	20	None

	4	Piston	Y	1	0.1	100	50	None
	5	Piston Cover	Y	1	0.1	50	50	None
	6	Nose Cone	Y	1	0.1	100	50	Touching Build Plate
	7	Blade	Y*	3	0.1	30	50	None
	8	Shaft	Y	1	0.1	50	50	None
	9	Shaft Shroud	Y	1	0.1	15	50	None
Potor Assy	10	Nose Cone Tip	Y	1	0.1	100	20	Touching Build Plate
ROLUI ASSY	11	M3 Nut	Ν	6				
	12	Pitch Bearing	Ν	6				
	13	M5 40mm	Ν	3				
	14	M3 12mm	Ν	9				
	15	M4 50mm	Ν	3				
	16	M4 Nut	Ν	6				
	17	M3 25mm	Ν	3				
	18	M5 50mm	Ν	1				
	19	M5 Nut	Ν	1				
	20	Pitch Spring	Ν	1				

## MAIN LOCATION BEARING

Brand: EU Budget

Inside Diameter: 25mm

Outside Diameter: 37mm

Width: 7mm

Seals / Shields: Rubber Sealed

http://simplybearings.co.uk/shop/advanced search result.php?search in description=1&keywords=F680 52RS

### **PITCH BEARING**

Brand: EU Budget

Inside Diameter: 9mm

Outside Diameter: 17mm

Width: 4mm

Seals / Shields: Non

http://simplybearings.co.uk/shop/advanced search result.php?search in description=1&keywords=F689

#### **PITCH SPRING**

RS Pro Steel Alloy Compression Spring, 80.5mm x 8.63mm, 0.17N/mm

http://uk.rs-online.com

#### **SLIP RING**

<u>file://localhost/link http/::www.dx.com:p:4-wires-1-5a-240v-d12-5mm-micro-capsule-slip-ring-for-cctv-monitoring-robot-black-388255 - .WDXzrHcTmRu</u>

# Electrical

The Turbine Power Circuit shown is used to convert Alternating Current from each of the twostepper motor coils to Direct Current, smooth the signal and regulate the output.





- M Stepper Motor
- R Full Wave Rectifier
- NEMA11

C Capacitor Vr Voltage Regulator

Vishay VS-2KBP005, Bridge Rectifier, 2A 50V, 4-Pin D 44

Panasonic 4700?F 25 V dc Aluminium Electrolytic Capacitor, FC Radial Series 5000h Magnatec L78S12CV, Single Linear Voltage Regulator, 2A 12 V, 3-Pin TO-220

Stock no.: 468-1603 Stock no.: 315-0669 Stock no.: 633-032

**RS** Components Stock Numbers